OCTOBER 1 - 5, 2023

IEEE/RSJ International Conference on Intelligent Robots and Systems



 Motivation: The global challenges of a growing population are driving the need for increased food production. Precision agriculture helps boost productivity and sustainability.

2023-

iROS

 Solution: We present a novel method to mathematically model agrifood and render images of the agrifood in simulation to boost the detection performance with real data



• 3D model of Agrifood(olives [1] and oysters [2]) with added texture



Blender was used to create a simulated agrifood image











Synthetic 3D Modeling

Image-2-Image Translation







Agrifood Detection Enhancement with Synthetic Data

Yianni Karabatis^{*1}, Xiaomin Lin^{*1}, Miao Yu¹, Yiannis Aloimonos¹, John Reid² Maryland Robotics Center, University of Maryland⁷ Computer Science Department, University of Illinois Urbana-Champaign²

System Overview



Domain Adaptation

The comparison of different I2I translation methods.



Input image, ground truth, transited image of CUT, QS-Attn, SRUNIT, VSAIT

Results

- Achieving a state-of-the-art for live and oyster detection.
- The detection result is improved when combining synthetic dataset with real dataset for training

[1] Karabatis, Y., Lin, X., Sanket, N. J., Lagoudakis, M. G., & Aloimonos, Y. (2023). Detecting Olives with Synthetic or Real Data? Olive the Above. 2023 IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS). IEEE.

[2] Lin, X., Sanket, N. J., Karapetyan, N., & Aloimonos, Y. (2023). Oysternet: Enhanced oyster detection using simulation. In 2023 IEEE International Conference on Robotics and Automation (ICRA) (pp. 5170-5176). IEEE

Real Agrifood Data